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Deyo et al.

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(54) **LOADER BUCKET CONSTRUCTION FOR ROBOT ASSEMBLY**

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(73) Assignee: **Clark Equipment Company**, Woodcliff Lake, NJ (US)

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(*) Notice: Under 35 U.S.C. 154(b), the term of this patent shall be extended for 0 days.

Drawings showing buckets in public use at least as early as 1991. Exhibits 1, 2 and 3.

(21) Appl. No.: **09/255,176**

Primary Examiner—Donald W. Underwood

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Related U.S. Application Data

(57) **ABSTRACT**

(60) Provisional application No. 60/104,183, filed on Oct. 14, 1998.

A bucket for a front end loader is formed with a minimum number of parts so that it can easily be assembled held in fixtures and welded with robot welders. The bucket includes a unitary panel that forms a bottom wall and a rear wall, with a curved junction wall between the bottom and rear walls. An integral top rail is formed at the upper edge of the rear wall for structural integrity. The formed top rail is made with a sloped top rail wall to increase the visibility of a load in the bucket to an operator in a cab of a skid steer loader. The bucket walls and parts which weld thereon have locating tabs and mating edges for locating the parts automatically, so that they can be welded into position. The bucket is made with brackets for mounting it onto a quick attachment plate of a skid steer loader.

(51) **Int. Cl.**⁷ **B65D 6/00**

(52) **U.S. Cl.** **414/722**; 29/466; 29/DIG. 48; 37/264; 37/398; 37/411

(58) **Field of Search** 414/722; 37/264, 37/398, 411, 450, 451, 452; 29/428, 464, 466, 469, 897, 897.2, 897.3, DIG. 48; 228/135, 182

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16 Claims, 12 Drawing Sheets

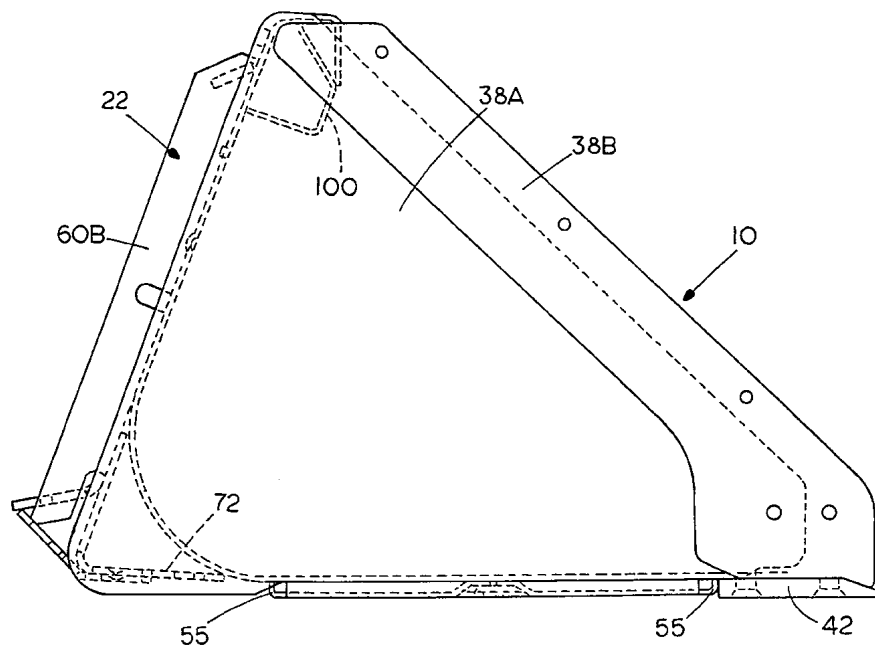
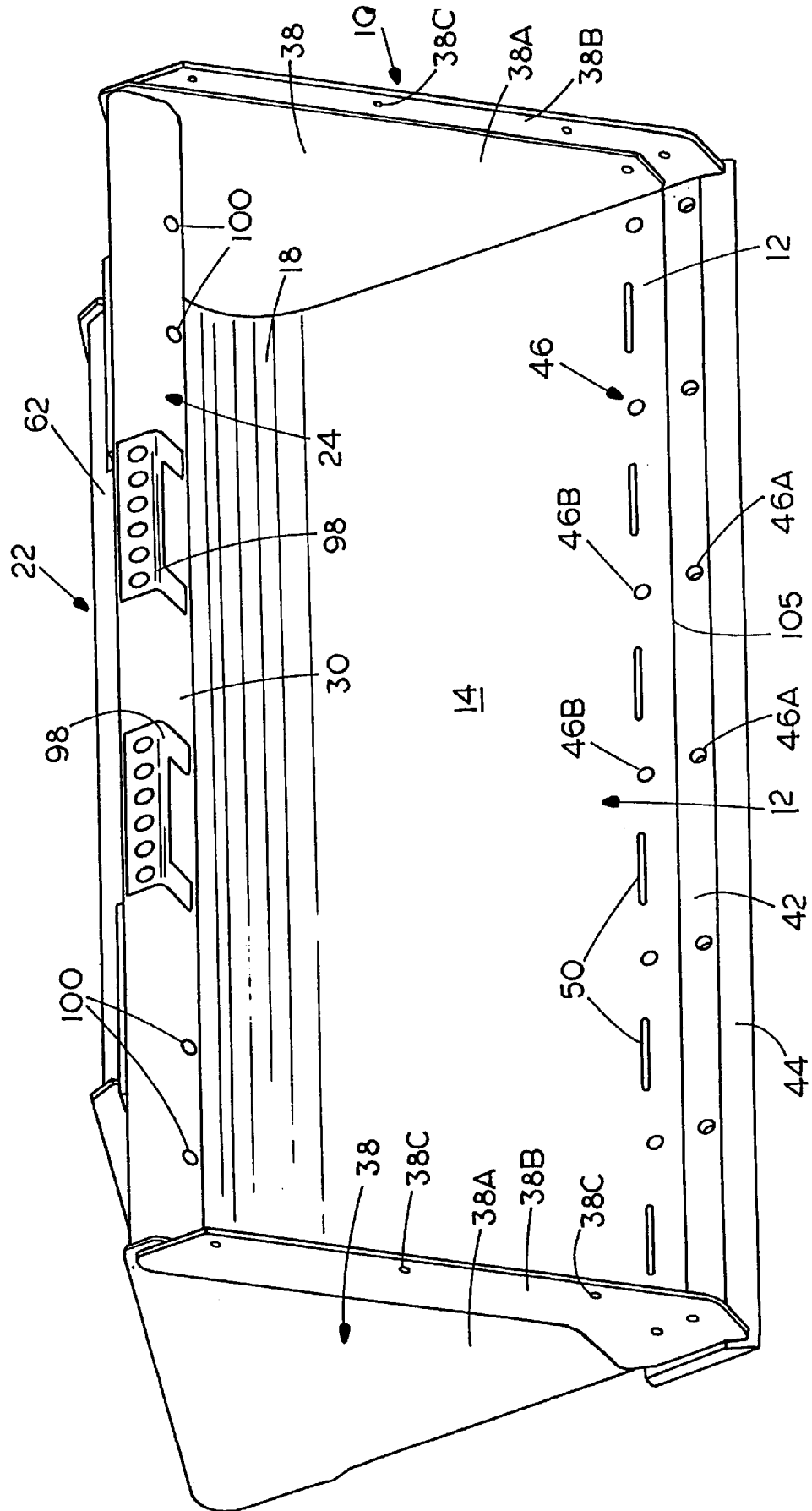


FIG. 1



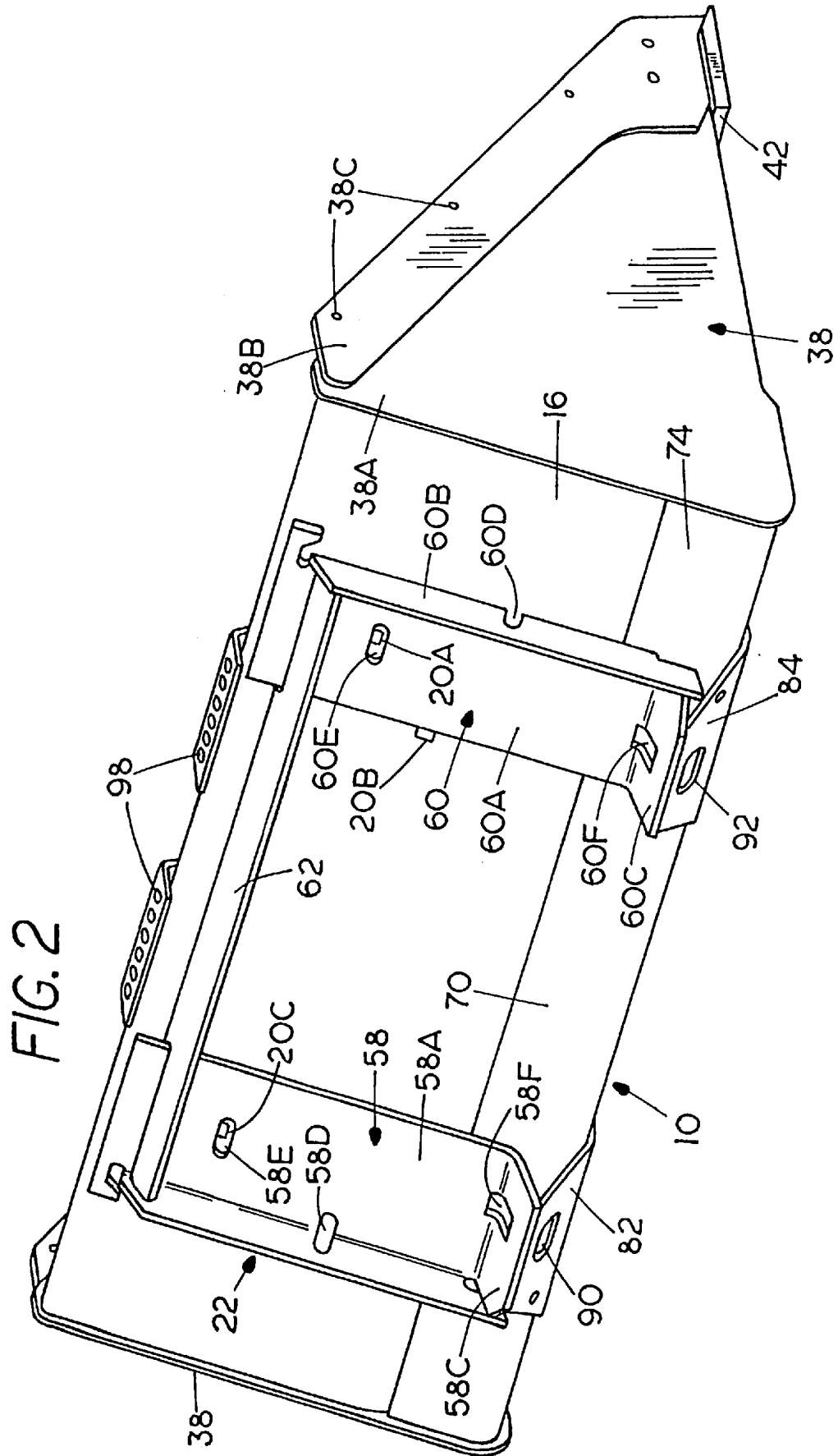


FIG. 3

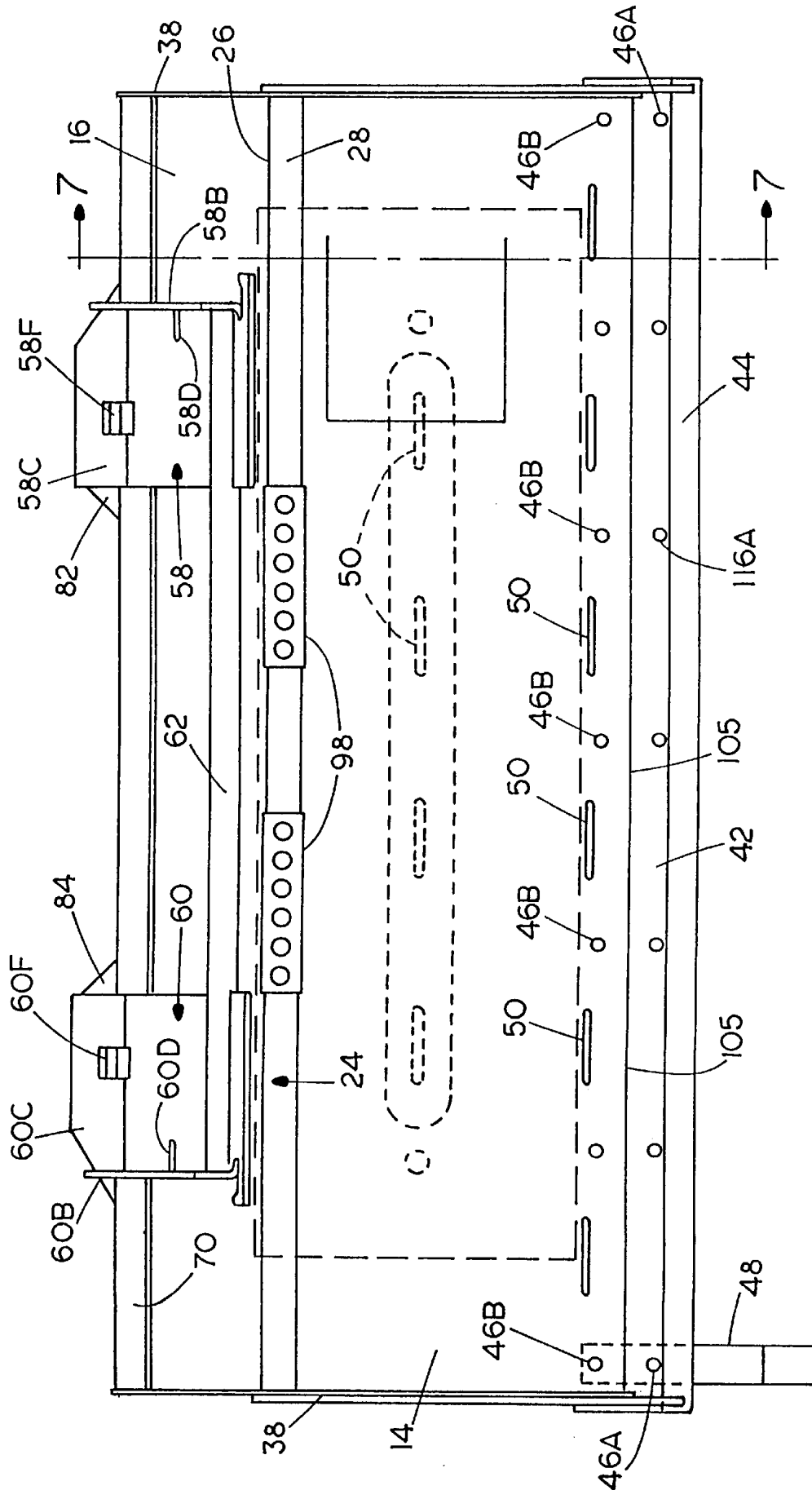
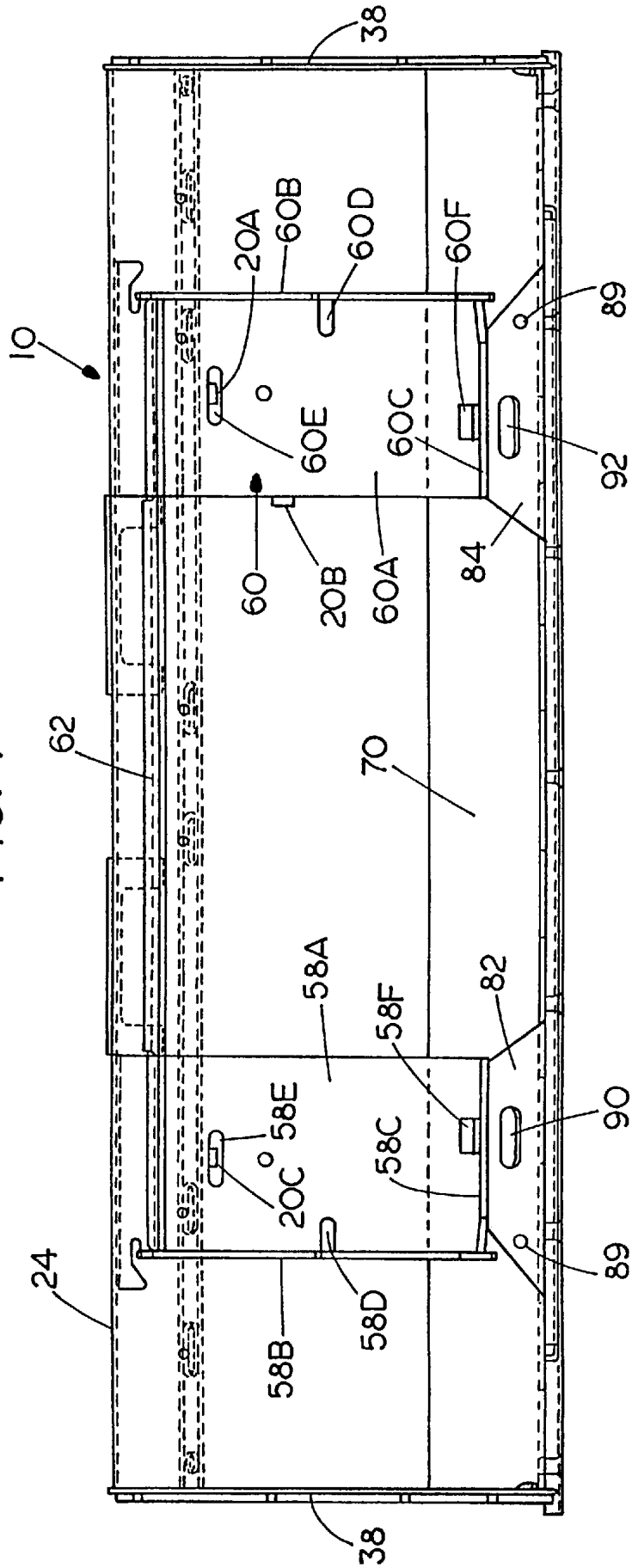
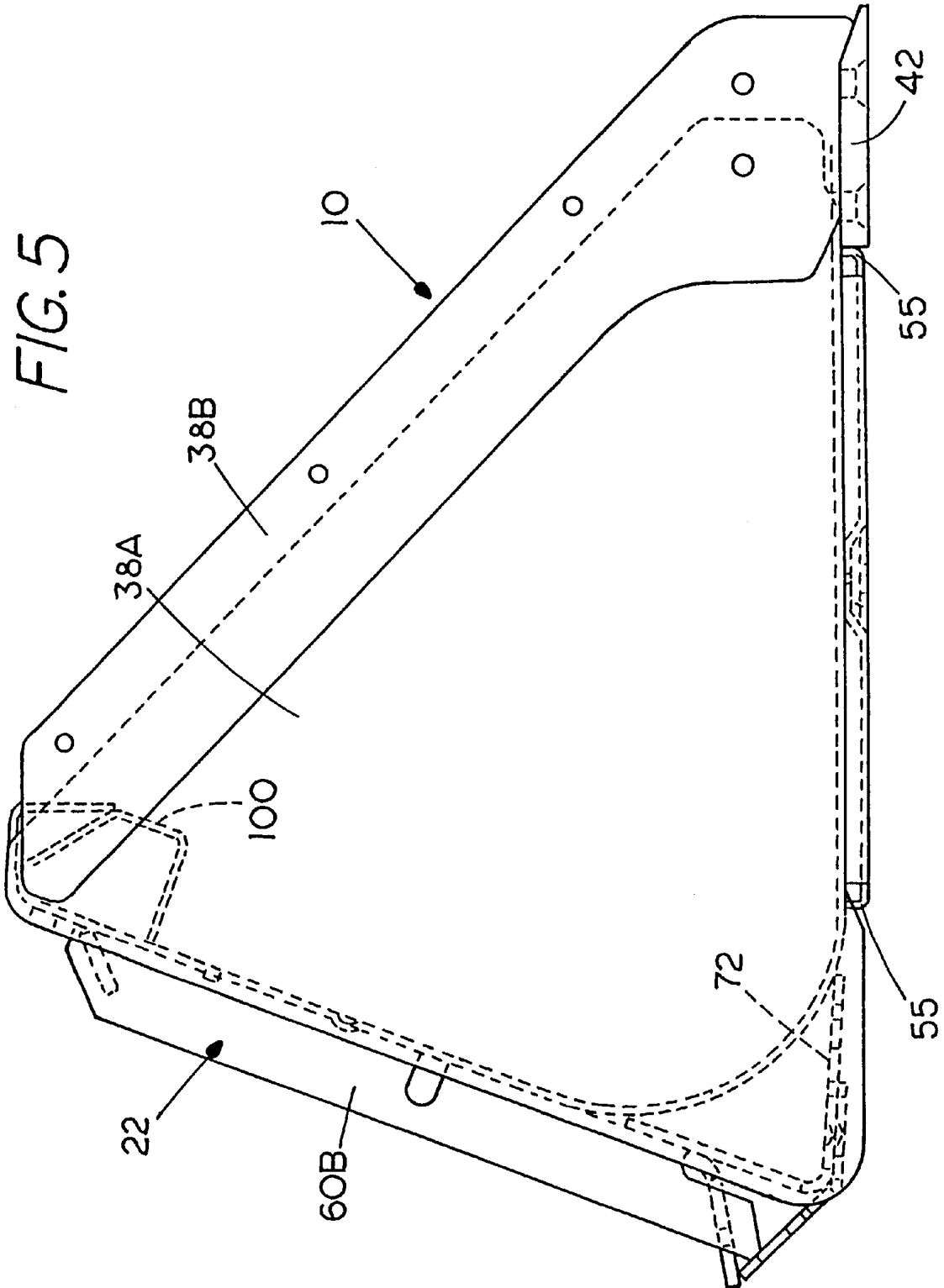
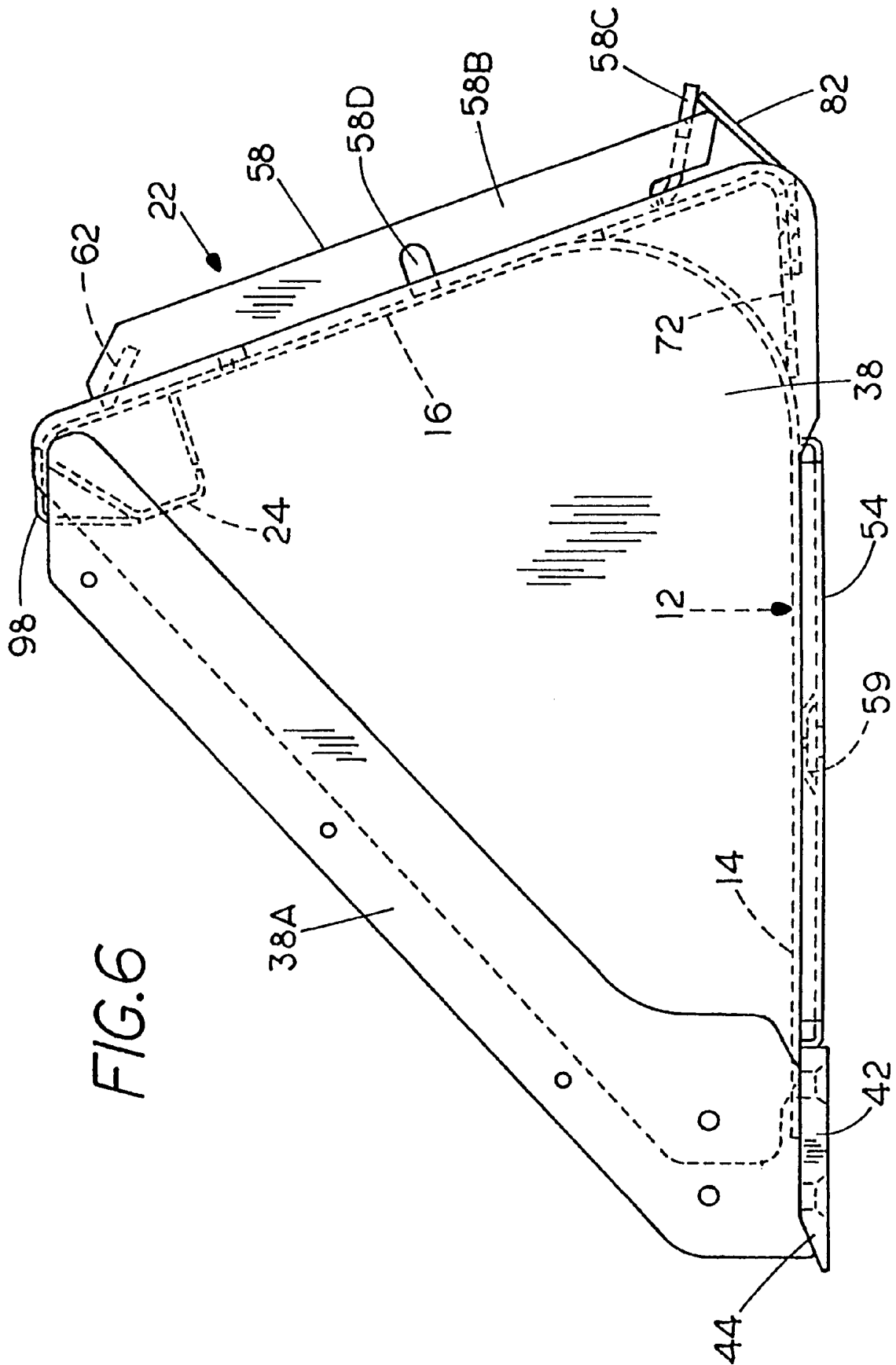


FIG. 4







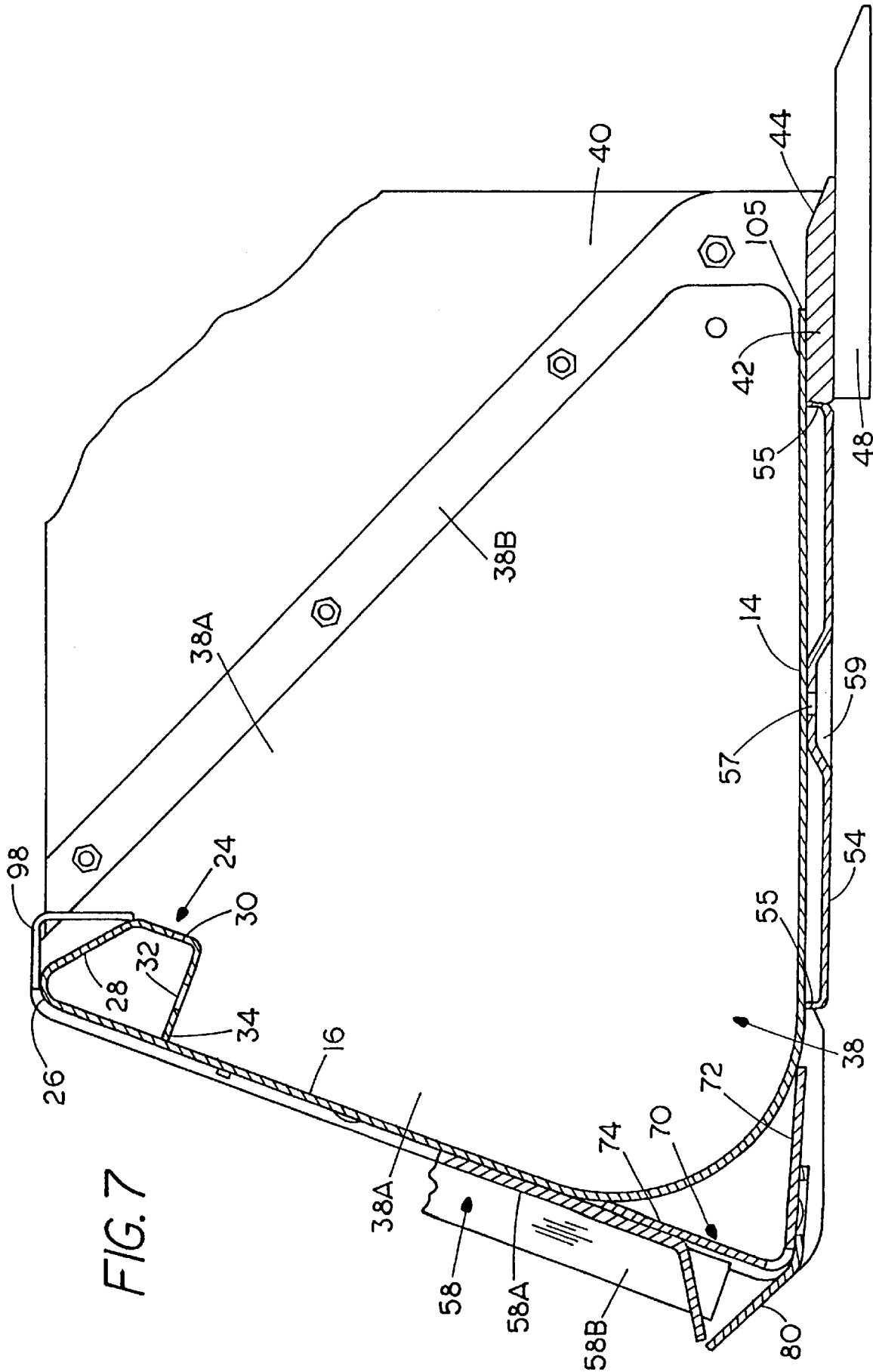


FIG. 7

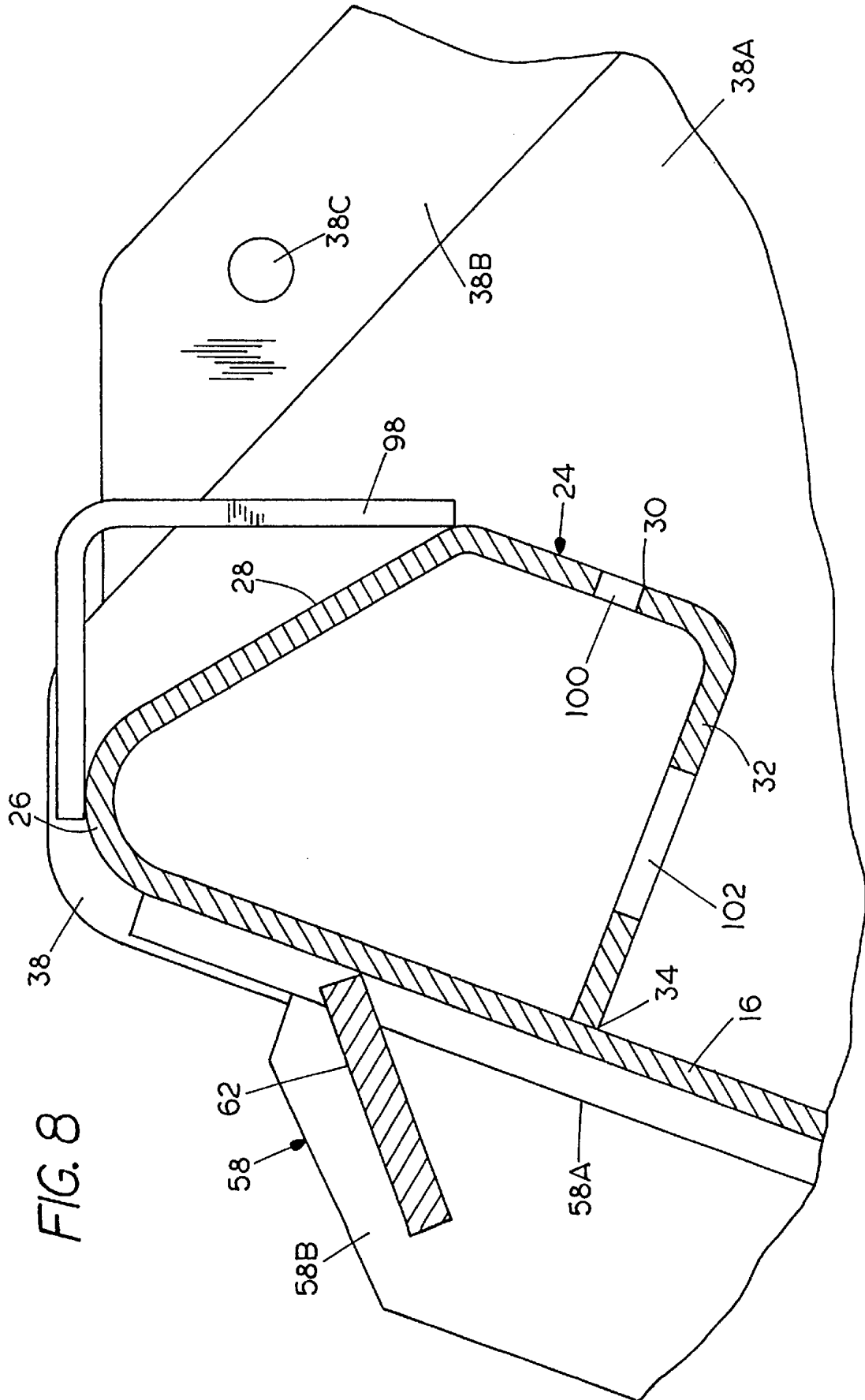


FIG. 9

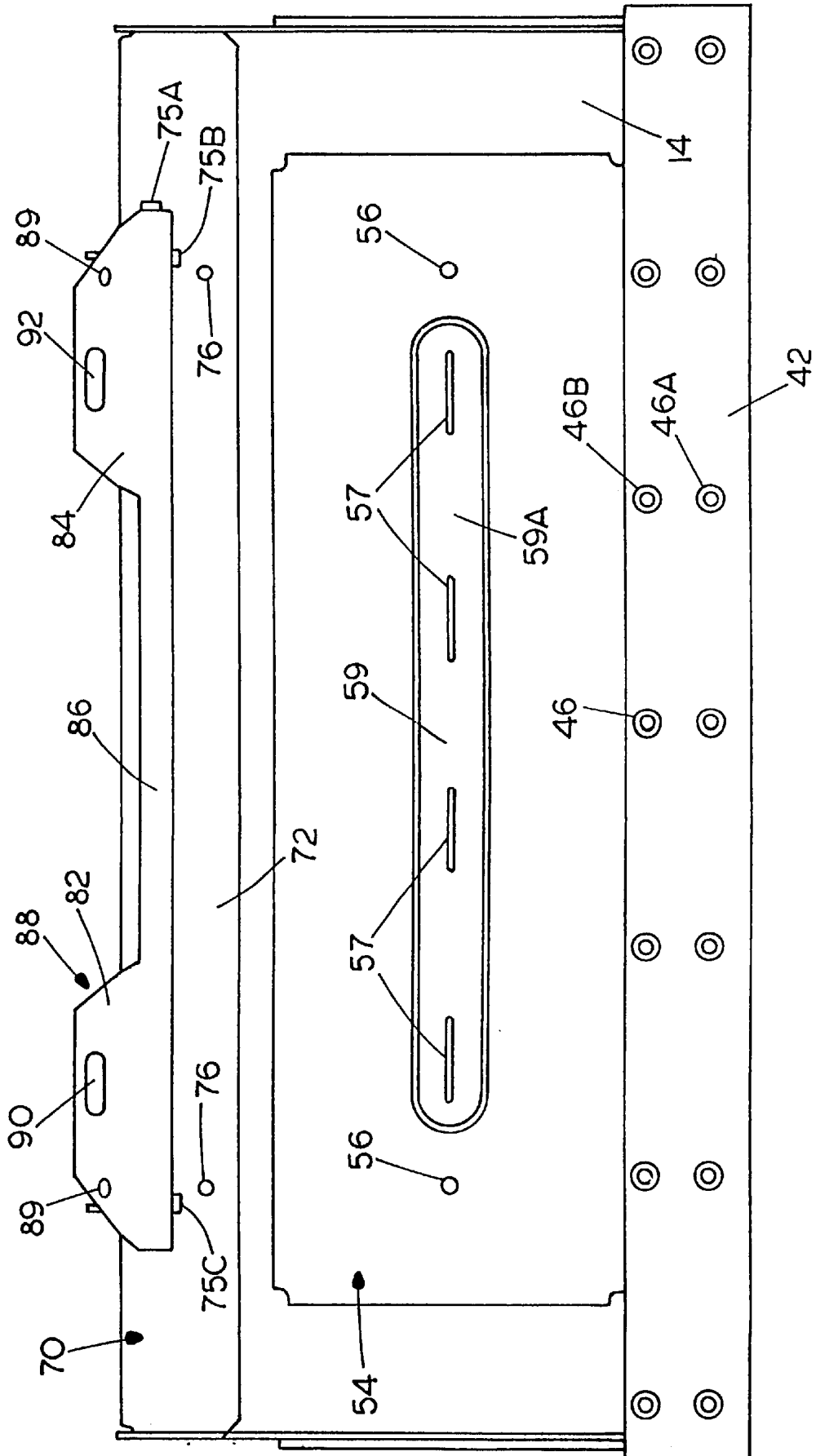


FIG. 10

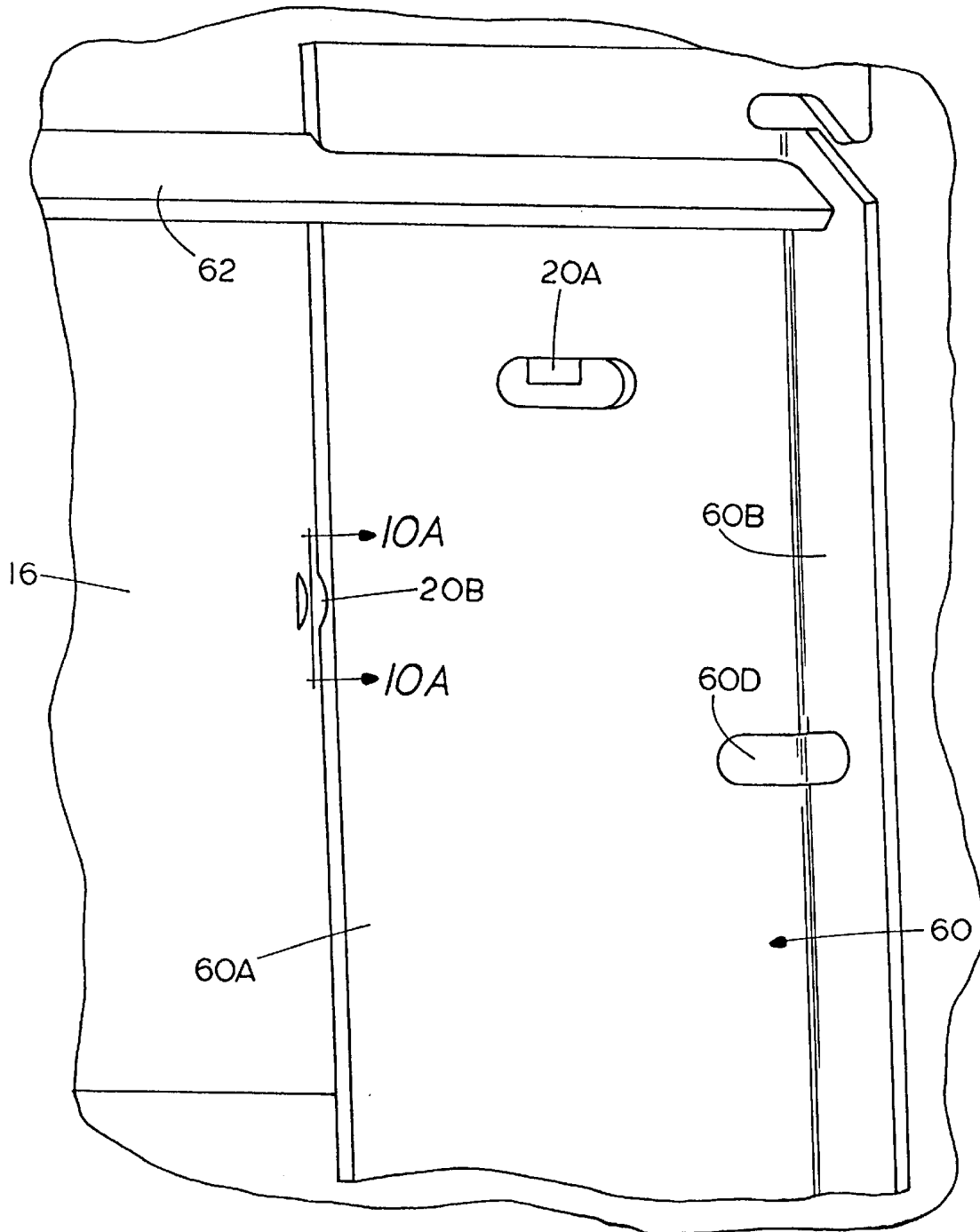


FIG. 11

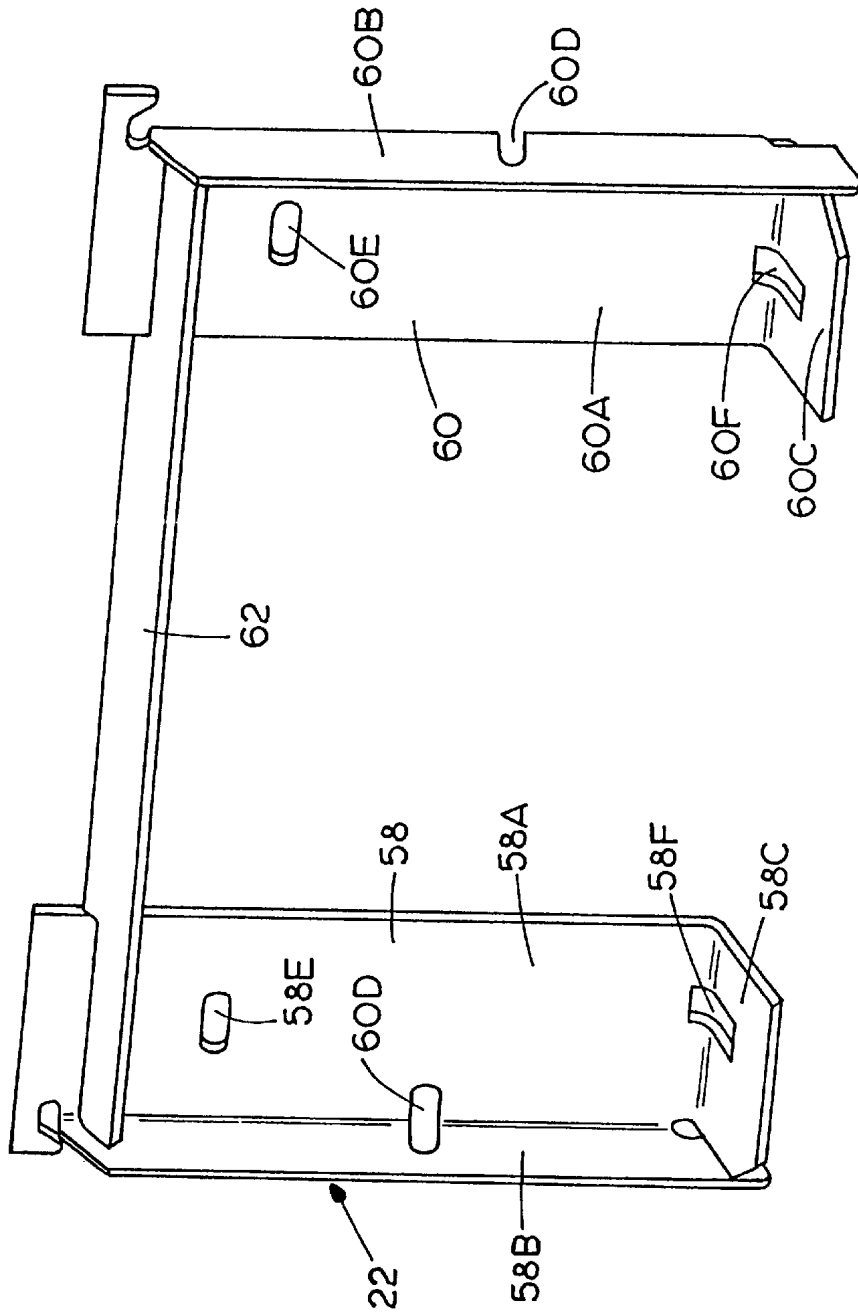
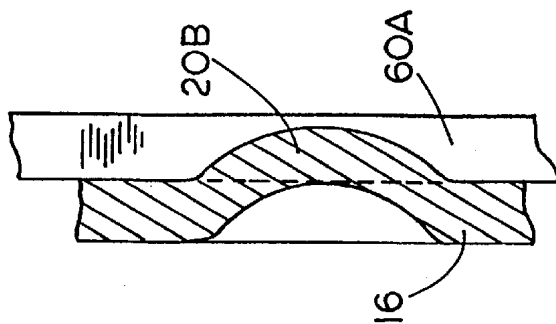


FIG. 10A



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LOADER BUCKET CONSTRUCTION FOR ROBOT ASSEMBLY

CROSS REFERENCE TO RELATED APPLICATION

This application claims priority on prior copending United States provisional application Ser. No. 60/104,183, filed Oct. 14, 1998.

BACKGROUND OF THE INVENTION

The present invention relates to a bucket construction for a bucket of a front end loader, which is made in a manner that permits automated or robot assembly and final welding of the parts and subassemblies.

Prior art buckets for front end loaders are generally welded assemblies, which require a large amount of hand welding and assembly, and thus the cost is increased. In many instances the bucket parts and subassemblies are assembled in a manner so that a robot controlled welding head cannot access the desired weld line.

The prior art buckets also are made of many individual pieces that require welds for assembly. Thus reducing the number of parts is desirable.

SUMMARY OF THE INVENTION

The present invention is a bucket for a front end loader that is simplified in construction so that the parts can be handled with robots and tack welded in place. The robots used can hold the critical dimensions of brackets used for the attachment of the bucket to a loader through a quick attach adapter.

The number of parts and subassemblies used in the final assembly and welding of the bucket is reduced in part by forming a bucket panel that forms the bottom wall and the rear wall in one piece joined by a curved junction portion. The reinforcing and attachment top rail at the top of the rear wall is formed as a single folded box cross section. After folding or forming the rail requires only an external weld that can be made with a robot welding head. The top rail is made so that it tapers down in a forward direction to increase the visibility of a load to an operator in the cab of a skid steer loader having a bucket made according to the present invention.

The bucket walls and parts have locating tabs formed to provide reference edges that are engaged by edges on the part to be located. Outer edges of the parts are used, as well as edges of slots formed for the express purpose of alignment. The parts that need to be manipulated are provided with robot grip attachment holes so the same robot can be used for many different types of buckets.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a top front perspective view of the bucket of the present invention;

FIG. 2 is a rear perspective view of the bucket of FIG. 1;

FIG. 3 is a top plan view of the bucket of FIG. 1;

FIG. 4 is a rear elevational view of the bucket of FIG. 1;

FIG. 5 is a side elevational view of the right side of the bucket of FIG. 1;

FIG. 6 is a side elevational view of the left side of the bucket of FIG. 1;

FIG. 7 is a sectional view taken on line 7—7 in FIG. 3;

FIG. 8 is an enlarged sectional view of a top rail of the

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FIG. 9 is a bottom plan view of the bucket of FIG. 1;

FIG. 10 is a fragmentary rear view of a mounting bracket subassembly on a rear wall of the bucket showing locating tabs and edges for locating mounting bracket parts for robot assembly;

FIG. 10A is an enlarged sectional view taken on line 10A—10A in FIG. 10;

FIG. 11 is a perspective view of a bucket adapter mounting bracket subassembly to show details of the mounting bracket; and

FIG. 12 is an exploded view of the parts assembled by robots during the final welding stage.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

A bucket 10 is shown assembled in FIGS. 1 and 2 and is made with a minimum number parts and subassemblies and is manufactured by robot methods. The bucket 10 has a main single sheet wrap around panel 12 that forms a bottom panel or wall 14 and an upright rear wall 16, that joins the bottom wall in a curved junction wall 18. The rear wall 16 has a plurality of formed tabs 20A, 20B and 20C, (FIG. 2) that are used for locating parts to be attached to the wrap around panel. The tabs 20A, 20B and 20C are used for locating an attachment adapter 22 that is a welded mounting bracket subassembly at the time of final welding and assembly of the bucket.

FIG. 12 is an exploded view of the bucket showing the parts that are used in the final welding process. Reference can be made to the Figures as the description proceeds.

The rear or back wall 16 of the bucket formed by the wrap around panel 12 inclines forwardly from the curved junction wall 18 and terminates in a formed box section top rail 24. The top rail 24 can be rolled from the wrap around panel 12 and as best shown in FIG. 8, includes a top curved edge 26 that joins a downwardly and forwardly inclined wall 28 that tapers forwardly at a slope that is designed to increase the ability of an operator on a skid steer loader to see into the interior of the bucket when working. The top rail 24 has a forward wall 30 that is parallel to the rear wall 16. The forward wall joins a bottom wall 32 that has an edge the engages or is very close to the front or inner surface of the rear wall 16. In the final welding process, the junction line or seam 34 forming the edge of the bottom wall 32 that engages the front surface of rear wall 16 is welded to rear wall 16 with a welding head operated by a robot. The welding junction line along the edge of the bottom wall is open from below and can be reached by a robot welding head. The weld can extend all the way across the width of the bucket.

The bucket wrap around panel or sheet 12 has end plates 38 welded at opposite ends thereof, and the end plates each include the main panel 38A and the top support panel 38B, that has a series of holes 38C that are used for attaching wear plates or extension panels 40 shown in FIG. 7. The extension panels are used where less dense material is carried, although the main panels and top support panels, which are welded together, will hold the rated capacity of the loader on which the bucket is intended to be used. The auxiliary or extension panels 40 are optional. The end plates 38, each including a main panel 38A and a top panel 38B are tacked or tack welded as a subassembly prior to the final assembly welding of the parts shown in FIG. 12.

The wrap around panel 12 is the main structural compo-

components, including a bar **42** forming a cutting edge which extends all along and under the front edge of the bottom wall **14** of the bucket, which is part of the wrap around panel **12**. The cutter bar **42** has a tapered or sharpened leading edge **44** that extends forwardly of the bottom wall of the bucket. A series of holes **46** that are arranged in fore and aft extending pairs **46A** and **46B** and are used for bolting on teeth shown schematically at **48** in FIG. 7 after the welded assembly is made. The teeth are optional as well and in many applications the cutting edge is used without teeth, particularly when loading or handling loose material. The teeth **48** are used primarily for digging.

The wrap around panel **12** is held in a robot fixture and can be manipulated to invert it as needed. The top rail is formed before any assembly so the curved panel **12** with the formed top rail is shown in FIG. 12 before parts are welded to it.

The cutter bar **42** is tack welded in place in a first tack welding station after aligning the parts using the holes **46B** which aligned with holes **46B** in the bottom wall **14** (see FIG. 3). The bottom wall **14** also has a series of slots **50** formed therethrough which overlie the rear portion of the cutter bar **42**. These slots **50** are used for welding the cutter bar to the bottom wall **14**. This welding at the slots **50** can be a tack weld in initial assembly and full welding can be during final assembly welding of the bucket. The wrap-around panel is held in a robot fixture in a conventional manner as the parts are added to it during the final welding and assembly process.

The bottom wall or panel **14** is reinforced using a skid or wear plate **54** that is provided with spaced holes **56** (see FIG. 9) that are spaced for connection to robot grips that pilot into the holes and securely grip the plate **54**. The robot then places the plate **54** on the bottom wall and the plate **54** is tack welded to the bottom wall through slots **57**.

The mounting bracket subassembly **22** is mounted on the rear side of the bucket and used with a quick attachment plate on a loader such as a skid steer loader made by Melroe Company of Fargo, N.Dak., and sold under the mark "Bob-tach". Such a quick attachment plate is disclosed in U.S. Pat. No. 3,672,521. The mounting brackets **58** and **60** are initially assembled together with an attachment lip **62** to form the subassembly **22**, and then the mounting brackets in the subassembly are located in portion and tack welded on the back or rear wall **16** of the wrap around panel. This is done right after the cutter bar is tack welded to the bottom wall **14**.

The brackets **58** and **60** are right and left hand and each has a flat plate portion **58A** and **60A** and bent up legs **58B** and **60B** on the outer sides. Additionally, the brackets have outwardly bent bottom flanges **58C** and **60C**, respectively. The subassembly is properly located using a robot for holding the subassembly and placing it onto the exterior of the back wall of the wrap around panel. The plate portions **58A**, **60A** have slots **58D** and **60D** that are formed before the legs **58B** and **60B** are bent up so there are slot sections in both the flat plate portions and the legs after the legs are bent. The slots **58D** and **60D** form holes for grippers of the robots used to hold the mounting bracket subassembly **22** for moving it toward and into contact with the outside of the rear wall. The brackets **58** and **60** also have positioning or locator slots **58E** and **60E** formed in the plate portions that have upper edges positioned to provide a reference locator line. The locator slots **58E** and **60E** are used for locating the subassembly **22** vertically on the top edges of locator tabs **20A** and **20C** for tack welding. Both mounting brackets **58B**

blank can be used for both brackets, and the right and left forms made by bending the legs **58B** and **60B** and the bottom flanges **58C** and **60C** in opposite directions.

The rear or back wall **16** of the bucket has the three locator tabs **20A**, **20B** and **20C** partially punched out, as explained. The tab **20A** is positioned to fit into the slot **60E**, and the tab **20C** is positioned to fit in the slot **58E** for vertical positioning of the bracket subassembly, and the tab **20B** is used to locate the upright or vertical edge of one of the brackets, as shown bracket **60**. The three point positioning positively locates the bracket properly. The tabs **20A**, **20B** and **20C** are formed as shown in FIG. 10A and each partial punch out is made to have a substantially straight, flat edge that engages the surface to be located, so the positioning is accurate.

The subassembly **22** then can be tack welded in position, at desired locations, while being held by the robot properly positioned by the alignment tabs **20A**, **20B** and **20C**.

The flanges **58C** and **60C** have slots **58F** and **60F** that are used for lock pins that are on the attachment plate used on the loader. Before final tack welding in place, these slots **58F** and **60F** are used to fit into a jig or fixture so that they are properly spaced and then the bracket subassembly **22** is tack welded in place.

The wrap around panel then is inserted and a corner bracket reinforcement or back brace is then placed into position and is best seen in FIG. 7. Reinforcement angle or back brace **70** is an angle shaped formed piece of metal indicated generally at **70** which has a leg **74** that extends up under the lower portions of the brackets **58** and **60** to brace the ends and reinforce them. The reinforcement is moved up between the rounded corner portion **18**, and the ends of the brackets **58** and **60**. The lower leg **72** of the reinforcement **70** is positioned to engage the rounded corner **18** near its junction with the bottom wall **14**, as shown in FIG. 7 in particular, and is tack welded in place. The bracket **58** is shown partially broken away and in section in FIG. 7.

The lower leg **72** of the reinforcement **70**, as can be seen in FIG. 9, has a pair of robot gripper holes **76**, **76** which are spaced apart the same distance as holes **56**, **56** of the reinforcing plate or wear plate **54**.

In addition, the lower leg **72** of the reinforcement member **70** has three alignment or locator tabs **75A**, **75B** and **75C** formed thereon. These locator tabs **75A**, **75B** and **75C** are formed in the same manner as that shown in FIG. 10A, and project out from the lower portion of the leg **72** of the reinforcement member **70**. The reinforcement member **70** is tack welded in place after the leg **74** is urged up between the lower ends of brackets **58** and **60** and the bucket rear wall and the edge of leg **72** rests on the lower side of the curved portion **18**.

The attachment brackets **58** and **60**, and in particular, the flanges **58C** and **60C** are mated with a lower latch plate assembly **80** that has flanges **82** and **84** on opposite ends thereof, and which are joined by a center member **86**. The assembly of the two flanges **82**, **84** and the member **86** is indicated at **88**, and this assembly is located in position by the tabs **75A**, **75B** and **75C**. Edges of flanges **84** are engaged by tabs **75A** for end use locating **75B** for fore and aft location. Tab **75C** locates flange **82** in fore and aft direction. It can also be seen that the flange assembly has robot gripper openings **89**, **89** on the outer edge portions of the flanges **82** and **84**, and these are again spaced the same distance apart as the robot gripper opening **76**, **76** so the same robot can be used for placing the latch assembly **88** into position against the locator tab **75A**, **75B** and **75C**.

Again there are three of the locator tabs for the assembly

these tabs while held by a robot gripper, and will be properly located so that latch openings **90** and **92** will be aligned with the slots **58F** and **60F**, so when lock members (not shown) from the quick attachment plate of a skid steer loader, such as that shown in U.S. Pat. No. 3,672,521, which is incorporated herein by reference, are placed into position. The lock member of the attachment plate slots **58F** and **60F**, and into the latch openings **90** and **92**, respectively on the flanges **82** and **84**.

This action will positively latch the bucket in place on the attachment plate, once the final assembly welding is done, and securely hold the bucket for working relative to the skid steer loader. The placing of the corner reinforcement **70**, and the assembly **88** onto the wrap around panel, at the rounded corner **18**, is done after the bucket has been inverted, and that is when the plate **54** is also installed.

As can be seen, the plate **54** is a formed plate, so that the slots **57**, **57** are in a channel **59** that is formed in the center portions of the plate **54**. A channel wall **59A** of the formed channel will engage the under surface of the bottom wall **14**, for welding. The edges of the panel or wear plate **54** can be formed, as shown by the wall portion **55**, in FIG. **5**, to engage the underside of the bottom wall **14** and the flanges are welded to the bottom wall.

Then, the end plates **38** can be placed onto the ends of the wrap around panel to form the bucket. The end plates can be held with suitable suction cups or the like with robots, and placed against the end edges of the wrap around panel, and tack welded in place around the top rail and along the junction with the top rail.

Brackets **98** on the top rail are steps that can be used for gaining access to a skid steer loader on which the bucket **10** is mounted. The steps can be added at any time. The front wall **30** of the top rail **24** has a plurality of openings indicated at **100** therein, and these are used for mounting attachments such as a grapple, or the like. In FIG. **4** and in FIG. **6**, wrench access openings **102** are shown on the bottom wall **32**, so that bolts that are passed through the openings **100** to secure an attachment in place can be tightened. This is conventionally done in formed box sections.

After the parts have been tack welded in place, the final welding can take place with continuous welds along the junction **34**, and continuous welds around the wrap around panel **12** where it joins the end plates **38**. A continuous weld would be used along the front edge **105** of the bottom wall, to weld the cutter bar securely. The corner reinforcing member **70** also can be welded continuously at the edges of legs **72** and **74**, except where leg **74** passes behind the brackets **58** and **60**. These welds are accessible, by having the formed top rail that can be welded with one continuous pass along the junction **34**, and then providing access for robot held welding heads around the periphery.

The use of gripper holes that are spaced identically on parts that are attached to the wraparound panel **12** insures that the robots will be easily installed on the parts, and the locator tabs shown make it so that the parts that are going to be welded in place are properly positioned by the tabs and then tack welded prior to final welding.

The flanges **58C** and **60C** are welded securely to the flanges **82** and **84** of the assembly **88**.

The exploded view of FIG. **12** shows the individual parts that are assembled together, to make the bucket. Sub-assemblies are made of the side plates and extensions and the attachment bracket, as stated, the cutter bar is tack

the bracket subassembly **22** is put into place on the back wall, the wrap around panel is inverted, and the reinforcing corner **70** and the reinforcing bottom plate **54** are tack welded into place. These two parts use identical robot gripper locator holes. The lower leg **70A** also has the locating tabs for holding the attachment flange assembly **88** into position for tack welding in place. Likewise, the tabs **20A**, **20B** and **20C** are used for locating the bracket subassembly **22**.

The end plates are welded into position and the bucket is fully assembled except for the steps **98** which are also added at the end.

The formed top rail **24** and locating tabs **20A**, **20B** and **20C** are key to automated manufacture by providing positively located accessible weld junctions for robot welding.

Although the present invention has been described with reference to preferred embodiments, workers skilled in the art will recognize that changes may be made in form and detail without departing from the spirit and scope of the invention.

What is claimed is:

1. A loader bucket having a continuous main bucket panel forming a bottom wall, and a rear wall, with an integral curved junction wall between the bottom wall and the rear wall, and an integrally formed top rail having a rounded corner forming an upper edge of the rear wall, a downwardly sloping, forwardly extending top wall, a front wall joining the forwardly and downwardly sloping top wall and extending substantially parallel to the rear wall, and an integral lower wall substantially perpendicular to the rear wall and extending to the rear wall.

2. The bucket of claim 1, wherein the rear wall has a plurality of partial punch out tabs protruding to an exterior of the rear wall forming locating tabs having edges facing toward the rounded corner, and a mounting bracket subassembly having a pair of uprightly extending brackets, said brackets being spaced apart and held together in the subassembly, each of said brackets having a slot for resting on an edge of a respective locating tab, and a third locating tab engaging an upright edge of one of the brackets.

3. The bucket of claim 2, wherein said brackets have legs bent outwardly therefrom and extending substantially perpendicular to the rear wall and on an exterior side thereof, said legs being along sides of the brackets adjacent respective ends of the bucket.

4. The bucket of claim 2, wherein said brackets have outwardly facing flanges at lower ends thereof, and each of the flanges having a slot for lock pins on an attachment plate used for attaching the bucket to a loader, said slots forming locators for properly spacing the subassembly of the brackets when supported on the locating tabs.

5. The bucket of claim 2 and a reinforcement back brace having a pair of integral legs bent from a corner portion, said reinforcement back brace being mounted to the exterior of the curved junction wall between the bottom wall and the rear wall of the main bucket panel, said integral legs being positioned to be substantially parallel to surfaces of the bottom wall and rear wall, respectively, and supporting lower portions of the brackets.

6. The bucket of claim 1, wherein the top rail lower wall that extends perpendicular to the back wall of the main panel has an edge where it joins the bottom panel accessible from below for robot welding.

7. The bucket of claim 4 and auxiliary brackets mounted onto a lower leg of the reinforcement back brace which is parallel to the bottom wall, the auxiliary brackets having portions extending to be adjacent to the flanges on the

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8. The bucket of claim 1 and a wear plate fixed to the bottom wall on an exterior side thereof, said wear plate having a center panel, and upright bent edges at a periphery thereof, and a channel shape formed portion in the center panel that protrudes in the same direction as the bent edges, said channel shaped member and said bent edges engaging the bottom wall and being fixed thereto.

9. The bucket of claim 8, wherein said channel in said wear plate has a plurality of elongated slots for permitting welding to the bottom wall of the bucket main panel.

10. The bucket of claim 9, wherein said wear plate has spaced apart robot gripper openings formed therein.

11. The bucket of claim 5 and planar end plates fixed to ends of said main bucket panel, along junction lines of both the bottom wall and the rear wall, said end plates extending outwardly beyond the curved junction panel of the main bucket panel and supporting end portions of the reinforcement back brace.

12. The bucket of claim 11 and a cutter bar welded on a front edge of the bottom wall, said bottom wall having a series of elongated, generally transversely extending spaced apart slots for providing welding edges to weld the cutter bar into position.

13. A welded construction loader bucket providing accessible edges for welding comprising a continuous main panel forming a bottom wall, a rear wall, and an integrally curved junction wall between the bottom wall and the rear wall, the

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bottom and rear walls defining a bucket with a forward edge and a top edge, a pair of end walls welded to ends of the main panel, a top rail, integrally formed from the main panel at the top edge of the rear wall, the top rail having a downwardly sloping, forwardly extending rail top wall, a forward rail wall joining the forwardly and downwardly sloping rail top wall and extending substantially parallel to the rear wall, and an integral bottom rail wall substantially perpendicular to the rear wall having an edge welded to such rear wall, the edge of the bottom rail wall providing an edge for welding accessible for a robot welding head.

14. The bucket of claim 13, wherein the rear wall has a plurality of partial punch out locating tabs protruding to an exterior of the rear wall defining locating edges for mounting brackets.

15. The bucket of claim 14 and a wear plate welded to the bottom wall on an exterior side thereof, said wear plate having upright bent peripheral edges, and a channel shaped formed portion in center portions of the plate thereof that protrudes in the same direction as the bent peripheral edges, said channel shaped formed portions and said bent peripheral edges engaging the bottom wall and being fixed thereto.

16. The bucket of claim 15, wherein said channel in said wear plate has a plurality of elongated slots therein for welding to the bottom wall.

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